Method Factors

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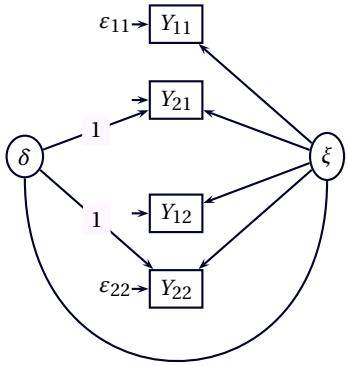
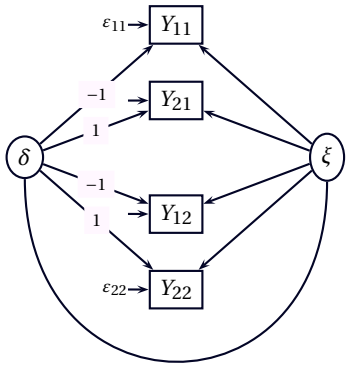
Latent State-Trait Models With Method Factors

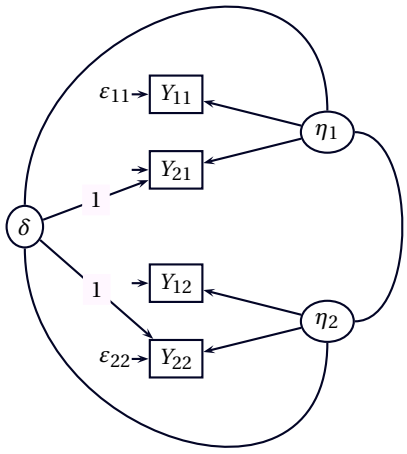
Singletrait Model With Method Factor, Reference Method



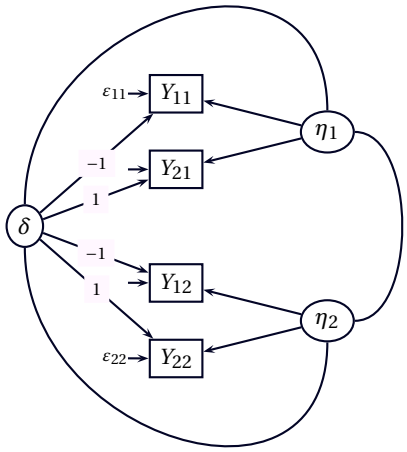
Singletrait Model With Method Factor, no Reference Method



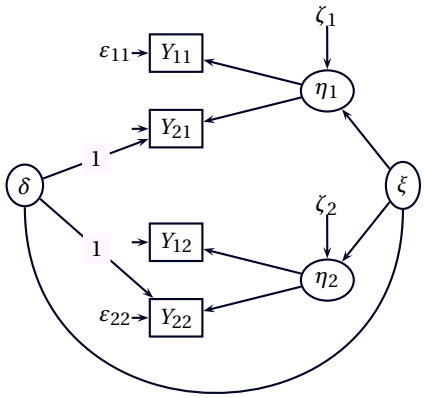
Multistate Model With Method Factor, Reference Method



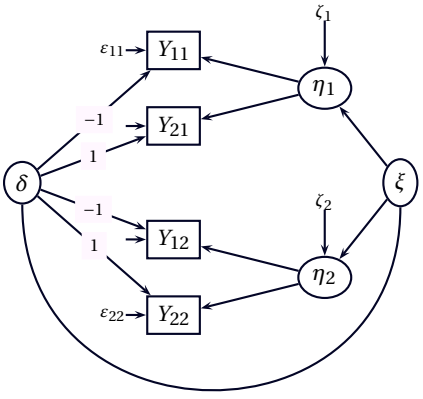
Mulitstate Model With Method Factor, no Reference Method



Multistate-Singletrait Model With Method Factor, Reference Method



Multistate-Singletrait Model With Method Factor, no Reference Method



Method Factor Derivation

Proof of:

$$\tau_{11} - \eta_1 = -\delta_1$$

$$\eta_1 = \frac{\tau_{11} + \tau_{21}}{2}$$

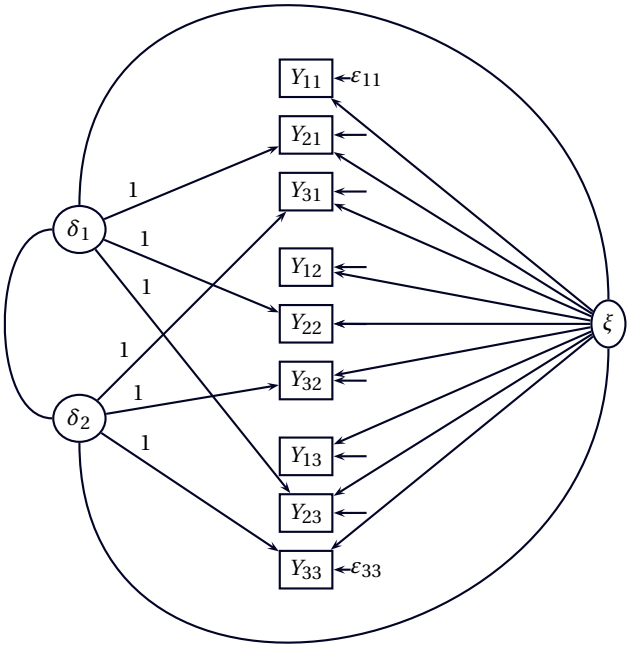
$$2\,\eta_1 = \tau_{11} + \tau_{21}$$

$$\eta_1 - \tau_{21} = \tau_{11} - \eta_1$$

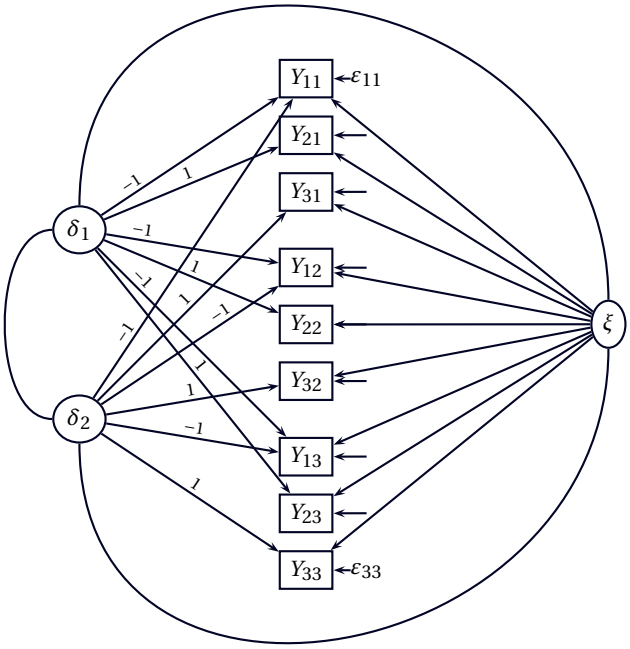
$$-\delta_1 = \tau_{11} - \eta_1$$

Models With Three Occasions of Measurement

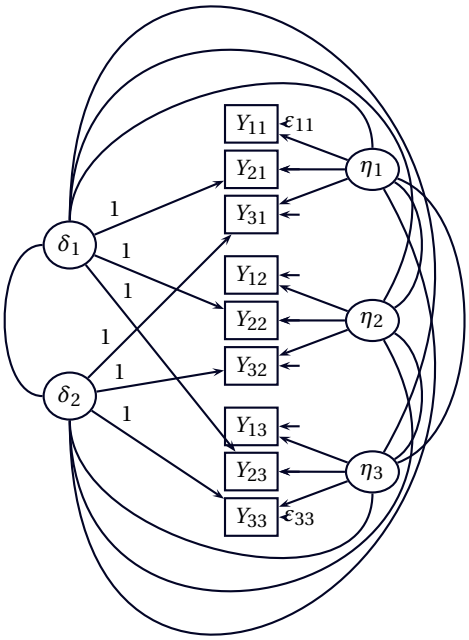
Singletrait Model With Method Factors, Reference Method



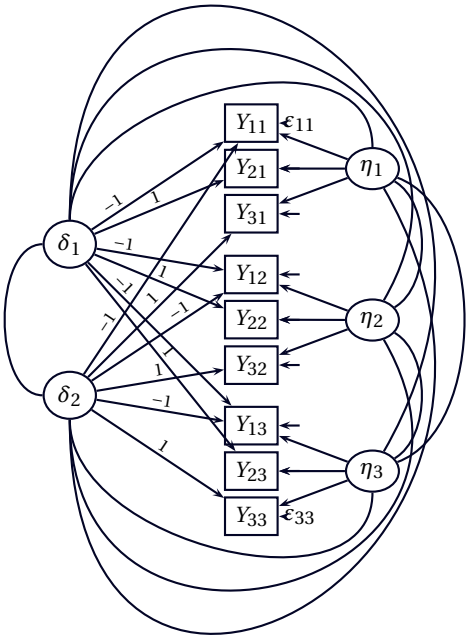
Singletrait Model With Method Factors, no Reference Method



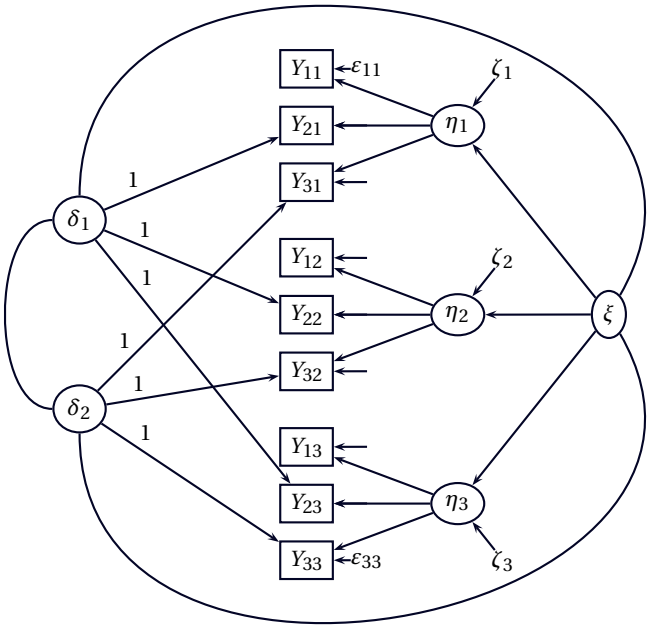
Multistate Model With Method Factors, With Reference Method



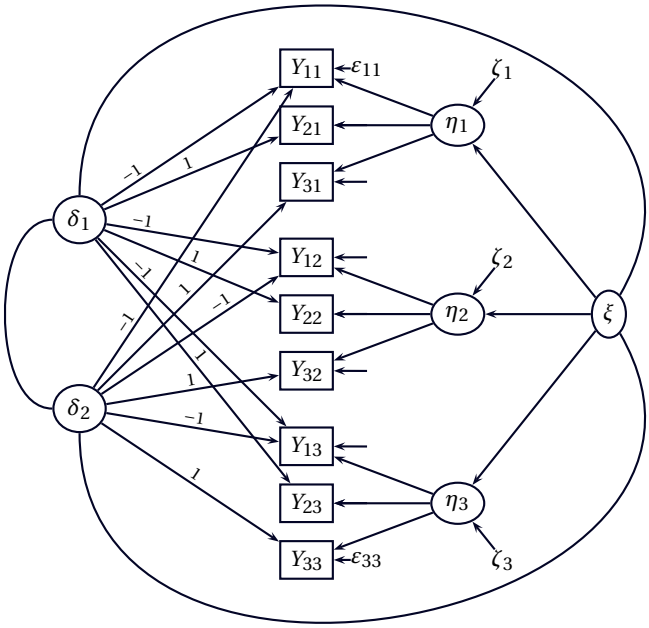
Multistate Model With Method Factors, no Reference Method



Singlestate-Multitrait Model With Method Factors With Reference Method



Singlestate-Multitrait Model With Method Factors, no Reference Method



Derivation

Proof of:

$$\tau_{11} - \eta_1 = -\delta_1 - \delta_2$$

$$\eta_1 = \frac{\tau_{11} + \tau_{21} + \tau_{31}}{3}$$

$$3\,\eta_1 = \tau_{11} + \tau_{21} + \tau_{31}$$

$$2\,\eta_1 - \tau_{21} - \tau_{31} = \tau_{11} - \eta_1$$

$$-(\tau_{21} - \eta_1) - (\tau_{31} - \eta_1) = \tau_{11} - \eta_1$$

$$-\delta_1 - \delta_2 = \tau_{11} - \eta_1$$